

HOMWORK 1

CEE 361-513: Introduction to Finite Element Methods

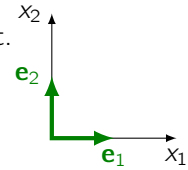
Due: October 1, 2018

NB: Students taking CEE 513 must complete all problems. All other students will not be graded for problems marked with *, but are encourage to attempt them anyhow.

PROBLEM 1

Unless otherwise specified, you may assume that $\{\mathbf{e}_i\}_{i=1}^d$ is a set of orthonormal basis associated with a set of cartesian coordinates $\{x_i\}_{i=1}^d$ (cf. the figure on the right). Use indicial notation when appropriate.

1. Show that for two vectors \mathbf{a}, \mathbf{b} the following holds $\mathbf{a} \cdot (\mathbf{a} \times \mathbf{b}) = 0$.
2. Let $d = 3$ and $\mathbf{u}(\mathbf{x}) = x_1 x_2 x_3 \mathbf{e}_1 + x_1 \mathbf{e}_2 + x_1 \mathbf{e}_3$ compute $\nabla \mathbf{u}$ and $\nabla \cdot \mathbf{u}$.
3. Let $d = 2$, $\mathbf{u}(\mathbf{x}) = x_1 x_2 \mathbf{e}_1 + x_1 \mathbf{e}_2$, and $\mathbf{v}(\mathbf{x}) = x_1 \mathbf{e}_1 + x_2 \mathbf{e}_2$. If $\mathbf{T} = T_{ij} \mathbf{e}_i \otimes \mathbf{e}_j = \mathbf{u} \otimes \mathbf{v}$, what are the values of T_{ij} .
4. What is the value of $\mathbf{I} : \mathbf{I}$, where \mathbf{I} is the identity tensor.
5. Let \mathbf{u} be a vector. Is $\mathbf{T}(\mathbf{u}) = \exp(\mathbf{u} \cdot \mathbf{e}_1) \mathbf{e}_1$ a tensor? Show why or why not.
6. Let \mathbf{u} be a vector. Is $\mathbf{T}(\mathbf{u}) = 10(\mathbf{u} \cdot \mathbf{e}_2) \mathbf{e}_1 + (\mathbf{u} \cdot \mathbf{e}_1) \mathbf{e}_2$ a tensor? Show why or why not.
7. * Show that $(\mathbf{u} \otimes \mathbf{v}) \cdot (\mathbf{A}) = \mathbf{u} \otimes \mathbf{A}^T \mathbf{v}$.
8. * Show that $\nabla \cdot (\psi \mathbf{u}) = \nabla \psi \cdot \mathbf{u} + \psi \nabla \cdot \mathbf{u}$ for $\mathbf{u} \in \mathbb{R}^d, \psi \in \mathbb{R}$.
9. * Show that $\nabla \cdot (\mathbf{u} \otimes \mathbf{v}) = \nabla \mathbf{u} \mathbf{v} + \mathbf{u} \nabla \cdot \mathbf{v}$.



PROBLEM 2

To practice with Python do the following operations

1. Let $\mathbf{u} = 1\mathbf{e}_1 + 2\mathbf{e}_2$. Construct a *unit* vector \mathbf{n} such that $\mathbf{u} \cdot \mathbf{n} = 0$. (Hint: create any vector \mathbf{v} that is not linearly dependent with \mathbf{u} , then let $\mathbf{w} = \mathbf{v} - \mathbf{v} \cdot \mathbf{u} / \|\mathbf{u}\|^2 \mathbf{u}$ and then let $\mathbf{n} = \mathbf{w} / \|\mathbf{w}\|$).
2. Let $\mathbf{u} = 3\mathbf{e}_1 + 2\mathbf{e}_2 + 4\mathbf{e}_3$, $\mathbf{v} = 5\mathbf{e}_1 + 1\mathbf{e}_2 + 4\mathbf{e}_3$. Construct a *unit* vector \mathbf{n} that is orthogonal to \mathbf{u}, \mathbf{v} . (Hint: \times)
3. Given two points $\mathbf{x}_a = 1\mathbf{e}_1 + 2\mathbf{e}_2$, $\mathbf{x}_b = 5\mathbf{e}_1 + 7\mathbf{e}_2$, construct a tensor \mathbf{T} that projects vectors along the direction of $\mathbf{a} = \mathbf{x}_b - \mathbf{x}_a$. Remember that a projection must satisfy $\mathbf{T}(\mathbf{T}(\mathbf{b})) = \mathbf{T}(\mathbf{b})$ for all vectors \mathbf{b} .
4. * Given a function $f(\mathbf{x}) = \sin(x_1) e^{x_2}$ derive ∇f and plot the vector field

PROBLEM 3

1. Let u, v be sufficiently smooth functions of x . Show step-by-step that

$$\int_0^\ell \left[\frac{d^2}{dx^2} \left(EI \frac{d^2 u}{dx^2} \right) \right] v dx = \int_0^\ell EI \frac{d^2 u}{dx^2} \frac{d^2 v}{dx^2} dx + \left[\frac{d}{dx} \left(EI \frac{d^2 u}{dx^2} \right) v \right] \Big|_0^\ell - \left[EI \frac{d^2 u}{dx^2} \frac{dv}{dx} \right] \Big|_0^\ell$$

where E, I are constants.

2. ★ Let $\boldsymbol{\sigma}(\mathbf{x}) \in \mathbb{R}^d \times \mathbb{R}^d$, $\boldsymbol{\sigma} = \boldsymbol{\sigma}^\top$, and $\boldsymbol{\eta}(\mathbf{x}) \in \mathbb{R}^d$ (with both $\boldsymbol{\sigma}$ and $\boldsymbol{\eta}$ being integrable and sufficiently smooth), show that

$$\int_{\Omega} (\nabla \cdot \boldsymbol{\sigma}) \cdot \boldsymbol{\eta} dV = \int_{\partial\Omega} \boldsymbol{\eta} \cdot \boldsymbol{\sigma} \mathbf{n} dS - \int_{\Omega} \boldsymbol{\sigma} : \nabla \boldsymbol{\eta} dV.$$